

# Route First Cluster Second-Based Formulations for a Variety of Routing Problems<sup>1</sup>

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In this talk, we observe that the partitioning of a giant tour for a multiple travelling salesman problem (mTSP) can be seen as a polynomially solvable 0-1 knapsack problem. Variations on this initial model permit to partition a giant tour for several types of routing problems. These include, among others, the mTSP with bounds on the number of cities to be visited (mTSP<sub>[K,L]</sub>), the VRP, the heterogeneous VRP, the mTSP with time windows and the multidepot mTSP (MmTSP).

The routing first-cluster second approach has already been considered by Beasley [1], Golden et al [2] and more recently by Imran et al [3] using dynamic programming or network based methods. The latter consist in constructing a cost network then computing a shortest path to optimally partition the giant tour. Though the optimal partitioning can be performed in a polynomial time, generalising this method can be problematic even for small changes as fixing the number of vehicles to an integer  $m$ .

Partitioning an optimal giant tour will not always produce an optimal solution as there is a lack of correlation between the quality of the giant tour and the solution of its corresponding optimal partitioning.

In order to tackle this, we put forward a hybridisation of the variable neighbourhood search heuristic, introduced by Mladenović and Hansen [4], with our models. This approach consists in partitioning an initial giant tour then perturbing it and splitting again a number of times. Reiterating this process in association with a reoptimizer such as 2-opt or an exact method permits to improve the initial solution.

For empirical testing, we assess the performance of our split-based VNS heuristic using two variants namely the mTSP and the mTSP<sub>[K,L]</sub>. Our hybrid approach performs well when compared to other approaches in literature.

Computing times needed to solve the various models are presented. The CPU time needed to split a giant tour depends on the problem nature. In a VRP situation, a giant tour can be partitioned for instances of up to 261 cities and 6 vehicles. A cost network approach is however preferred for larger instances if  $m$  is free using Dijkstra's algorithm or dynamic programming. On another hand, partitioning a giant tour for other variants such as the MmTSP can be performed quickly even for large instances. As an illustration only, the partitioning of a MmTSP 4460-nodes giant tour is performed within 2 seconds.

*Keywords* - routing problems, route first-cluster second, integer programming, VNS.

## References

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